VarioShaker 540.

Component separator for pick and place and flexible feeding.







More than just a simple component separator. The Varioshaker 270 is primarily used in the fields of pick and place and flexible feeding. In comparison to conventional systems, the VarioShaker 270 is easy to set up and configure as well as robust and uncomplicated in use. Components with different shapes can be separated by controlled movements. In addition to a web-based configuration for easy operation, the VarioShaker 270 has an I/O interface and can therefore be adapted to almost any robot.



www.variobotic.de









Contact and Support

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VarioShaker 540. Technical specifications.

Approx. 475 × 290 mm PE white
PE white
Plain
20 to approx. 100 mm (further part sizes possible after testing)
On request
Approx. 660 × 425 × 160 mm (L x W x H)
5°C - 40°C
27.5 kg
WebGUI via standard web browser

	+96 V / 4A	Power supply						
	+24V / 4A	(combine mass from 24 V and 96 V) the fuse is located in the housing						
	0 V							
	PE	Protective earth conductor						
Inputs 24 V DC max. 2,4 mA	I_EN	Enable / Start						
	I_Bit1	Binary coded sequence selection - examples:						
	I_Bit2		Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	
	I_Bit3	Sequence 1:	1	0	0	0	0	
	I_Bit4	Sequence 2:	0	1	0	0	0	
	I_Bit5	Sequence 3:	1	1	0	0	0	
	I_LED	Control input for transmitted light						
Outputs 24 V DC max. 100 mA	O_Rdy	Condition: ready						
	O_Bsy	Condition: busy						
	O_Res	Unassigned (reserved)						
	O_Bnk	Hopper on						
Output 24 V DC max. 500 mA	O_Top	Incident light (additional lighting, optional)						
Further connections	M12 cable (8-pin) 5m M8 cable (4-pin) 5m	Control line between VarioShaker and control box						
	Ethernet (TCP/IP)	Optional for cor	Optional for control					
	USB	USB port for update WebGUI						

Misprints and technical changes reserved, Status: 05/2021



